

# Foraging behaviour in small organisms

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# Solving foraging problems without a brain?

- Many cells have motility, e.g. flagella and cilia
- Many “aneural” can perceive chemical cues (and other cues) and elicit motor responses

# Why do microbes move?

Is space that heterogeneous? Yes, probably

And do they move non-randomly?

Do they show adaptive behaviour?

# Why move with less than mm/s?

- Foraging
- Predator avoidance
- Mate search
- Avoidance of abiotic stress



# Consequences of microbial movement

- Predator - prey interactions (encounter rates)
- Biomass turnover  $\gg$  rates of biogeochemical cycling

# How to aggregate in favourable locations?

Focus on how small organisms may exploit food patches

- Find food patches
- Stay in food patches
- Leave patches when food is depleted

# The problem



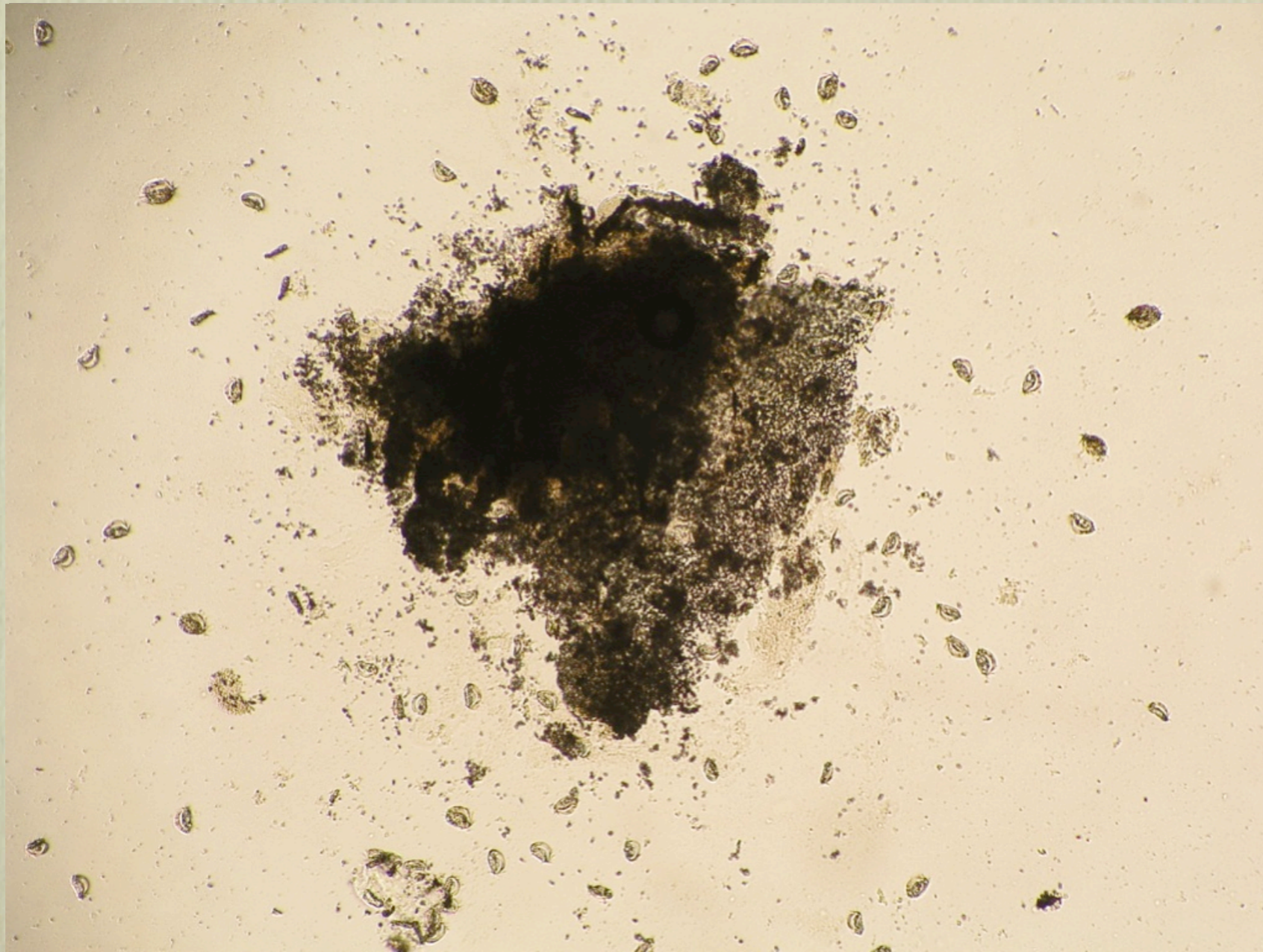
# Example: epibenthic ciliates



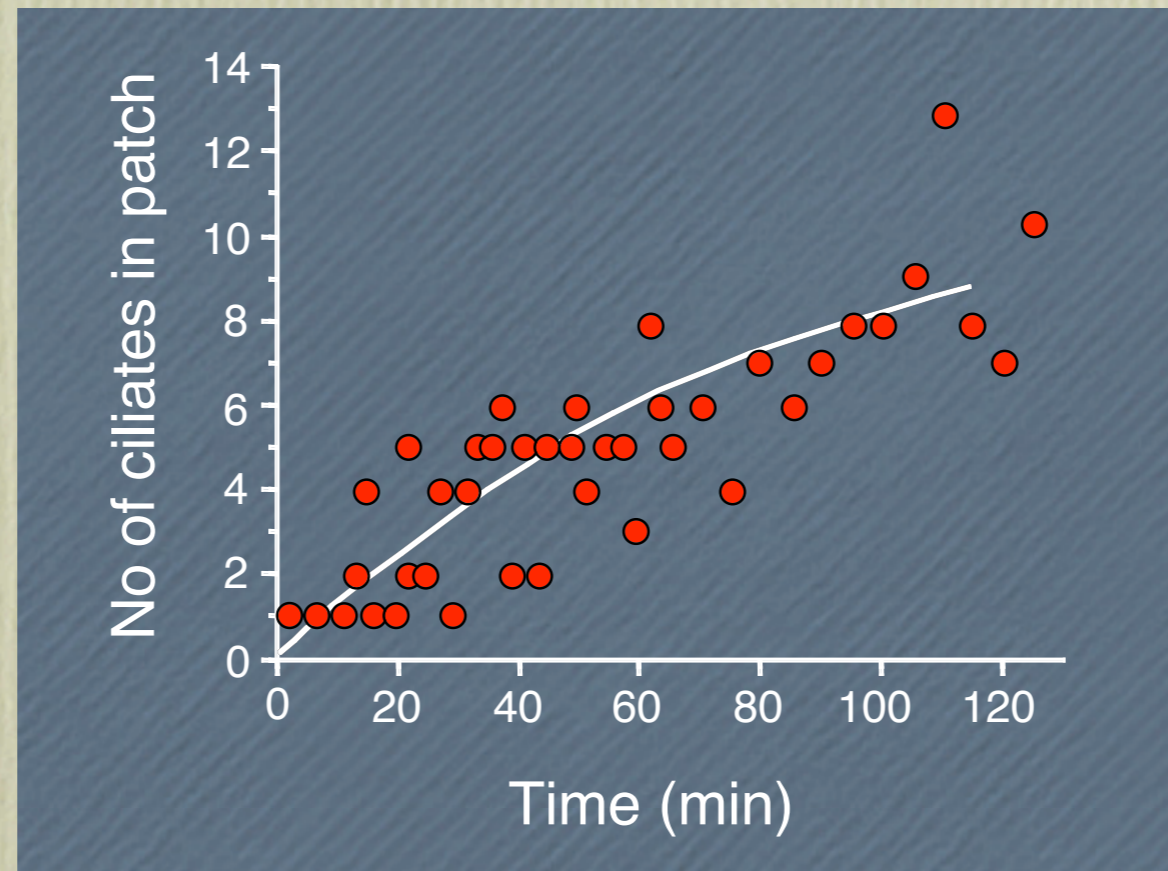
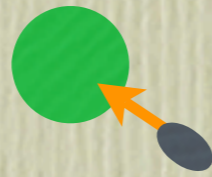
*Euplotes sp.*



# Aggregation in food patch



# What is making *Euplotes* accumulate?



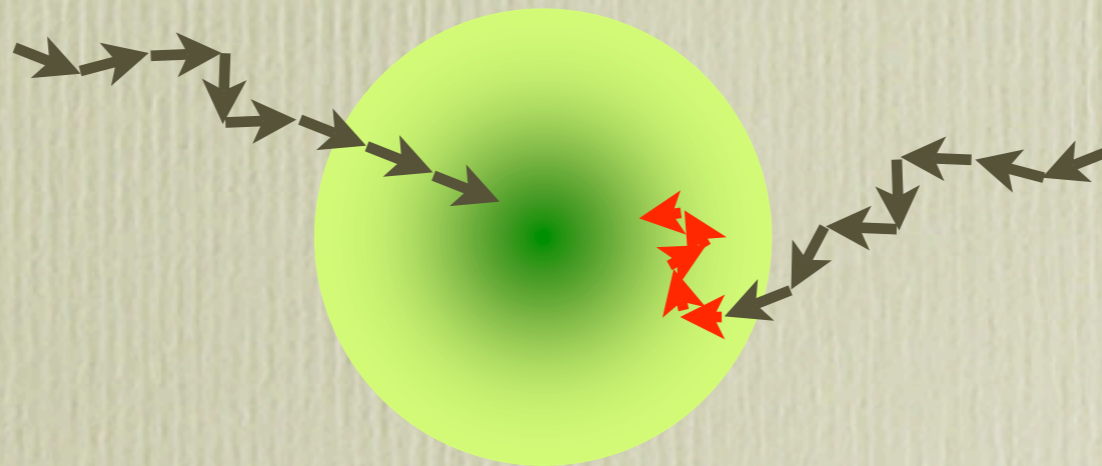
Jonsson & Johansson 1997

Accumulation with time

# Taxis or kinesis?

(Taxis is the movement in the direction of a stimulus gradient)

Kinesis is a change in movement in response to the intensity of the stimulus

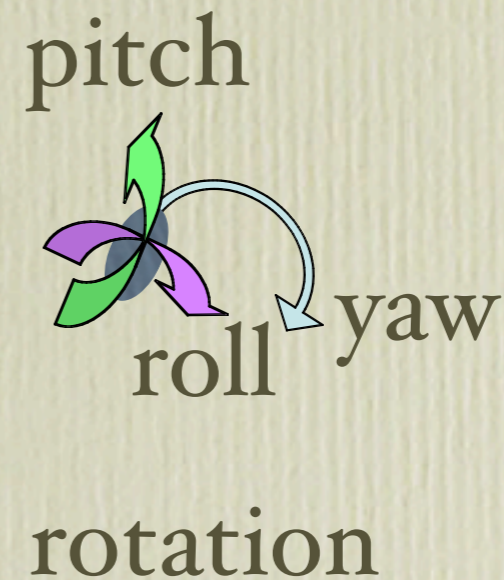
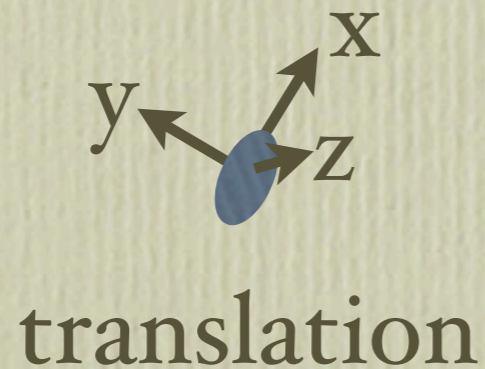


# Analysis of aggregation by modelling movement

- Define parameters that can describe movement patterns
- What movement patterns may lead to aggregation?

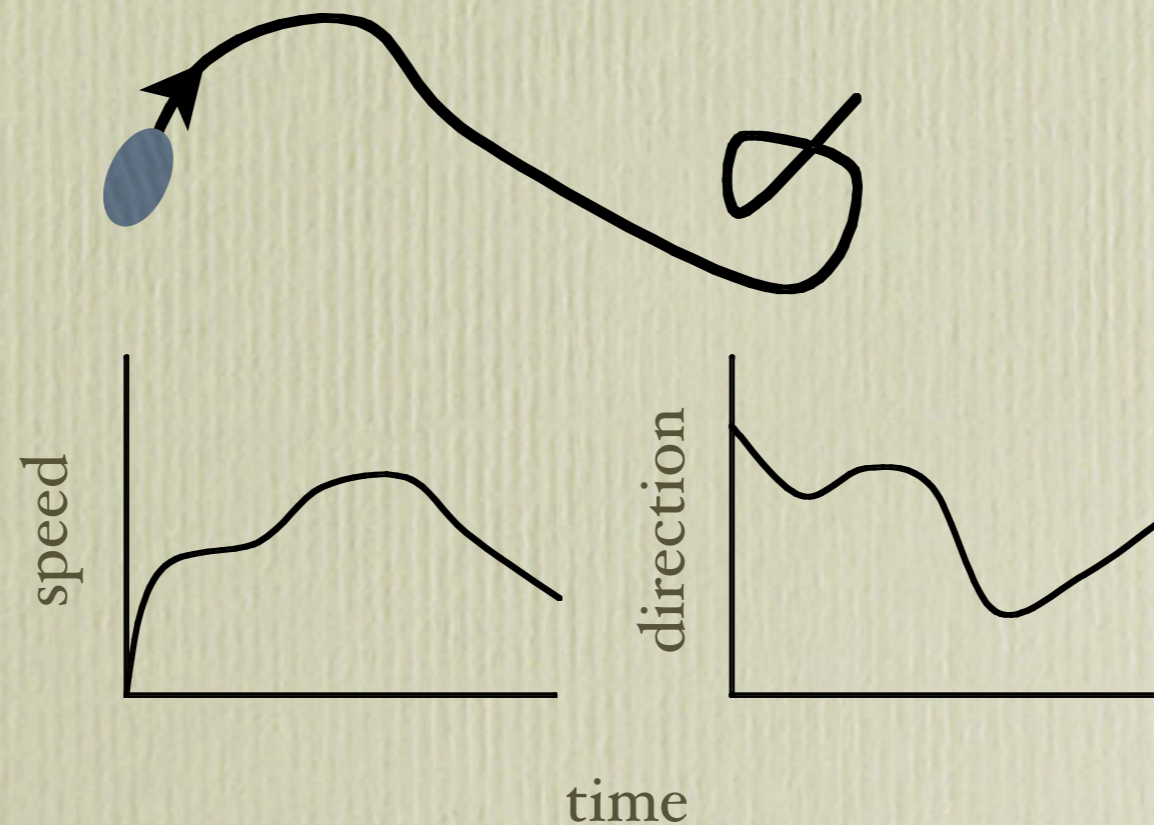
# Motion degrees of freedom

- 3 translational degrees of freedom
- 3 rotational degrees of freedom

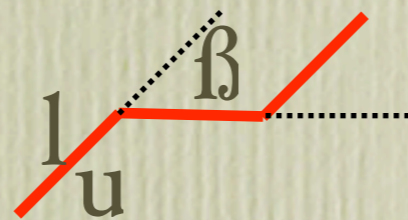
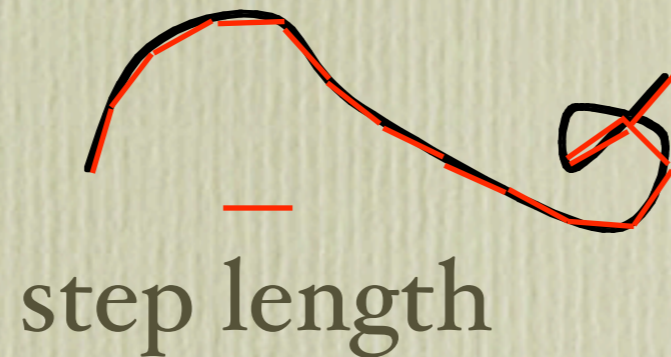


# Fundamental components of movements

- Velocity as a function of time



# Discretization of paths

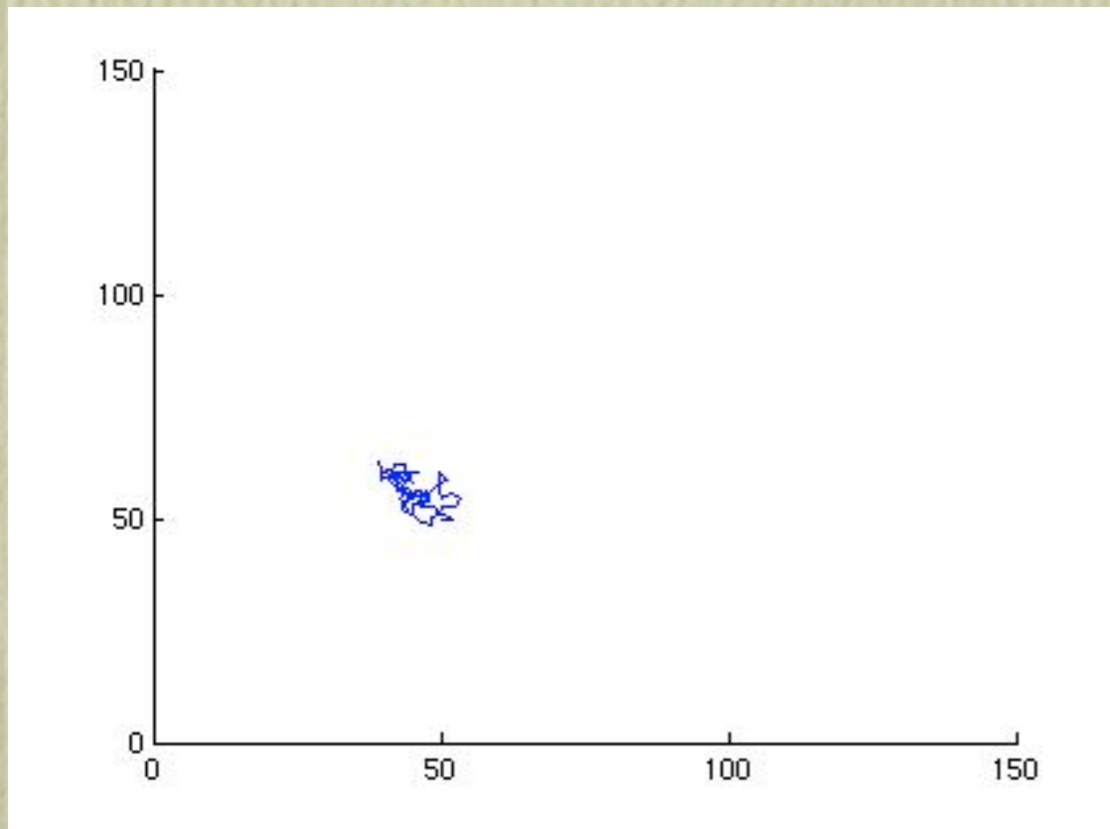


$u$  = speed

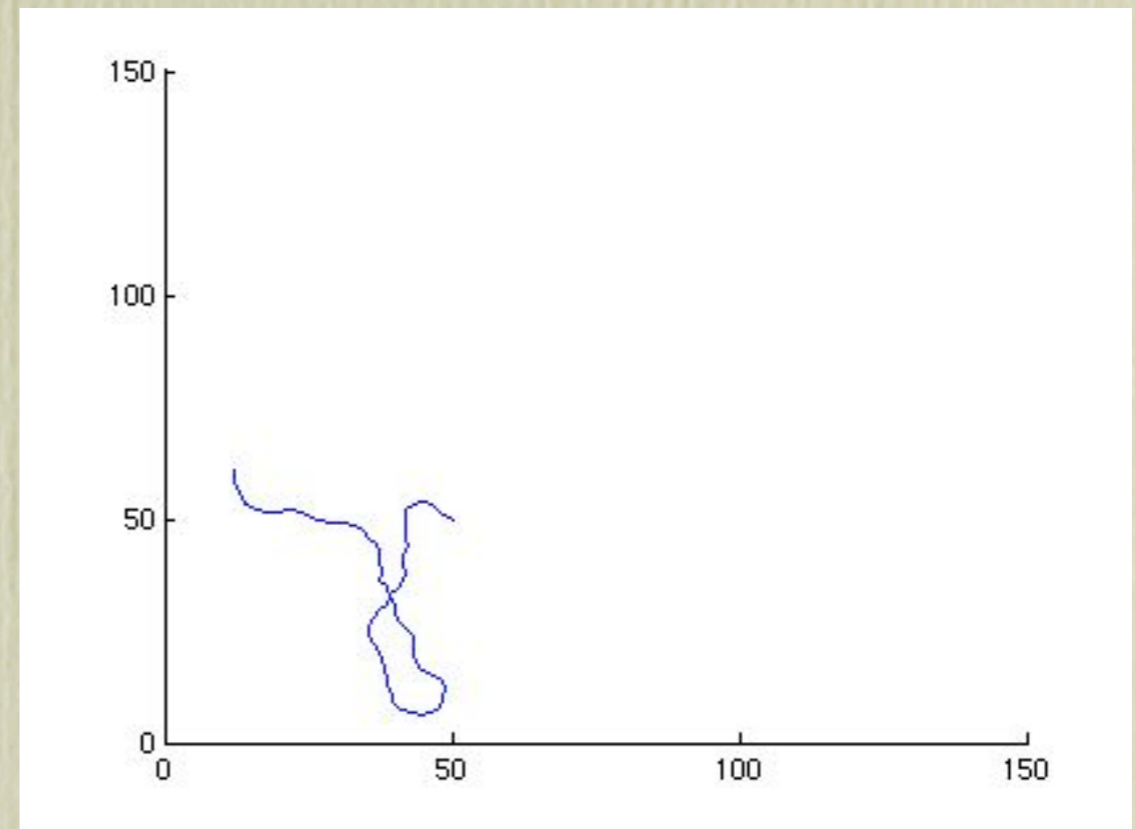
$l$  = step length

$\beta$  = angle of direction change


# Random walks



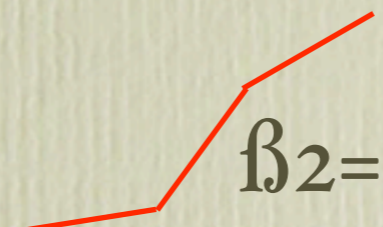
uncorrelated



correlated



$\beta = \pm\pi * \text{rand}$

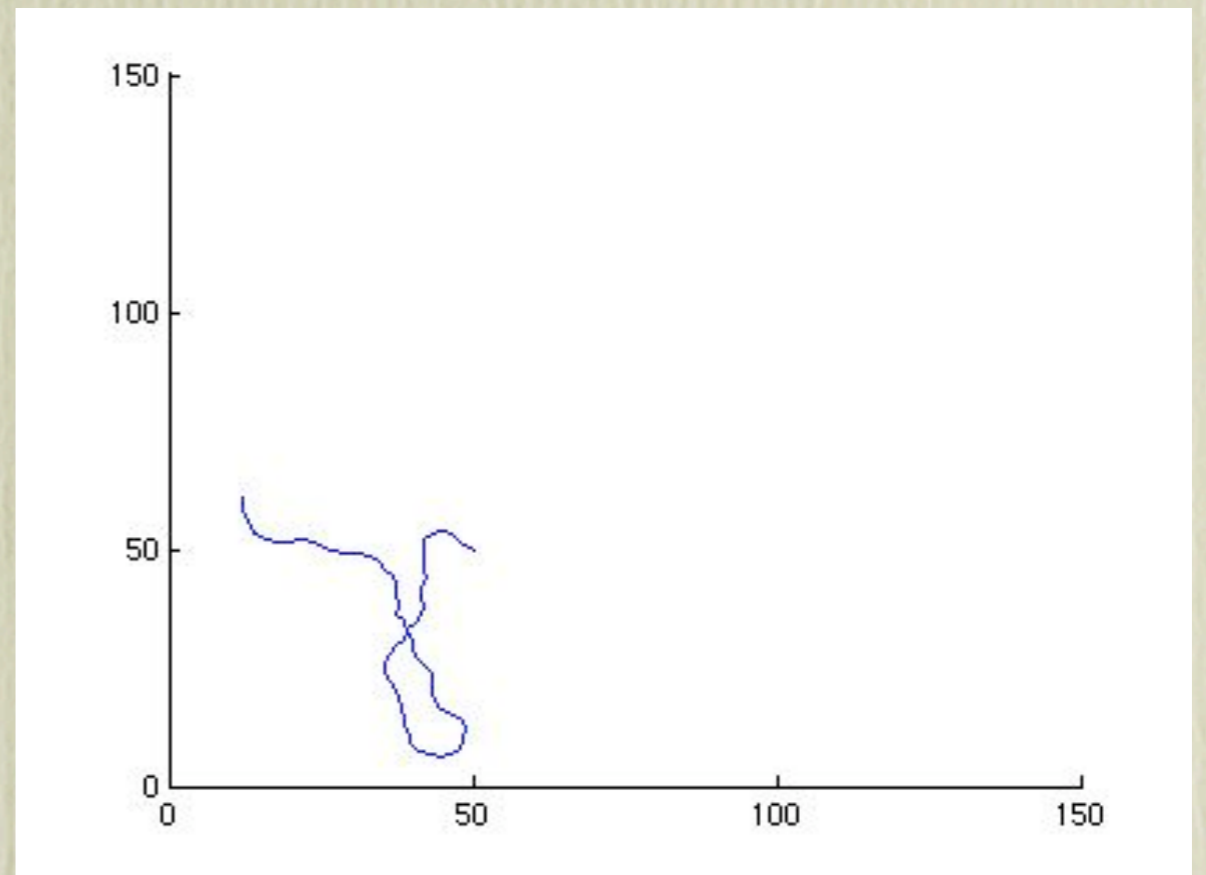


$\beta_2 = \pm < \pi * \text{rand} + \beta_1$



# Analysis of movement

- Primary parameters describing path
  - speed
  - frequency of direction changes
  - angular correlation
- Secondary parameters
  - sinosity
  - diffusion constant
  - fractal dimension



# Simulation of ciliate movement

select initial position  $(x(1), y(1))$

select a speed  $(u)$

for  $t=2$  to 100

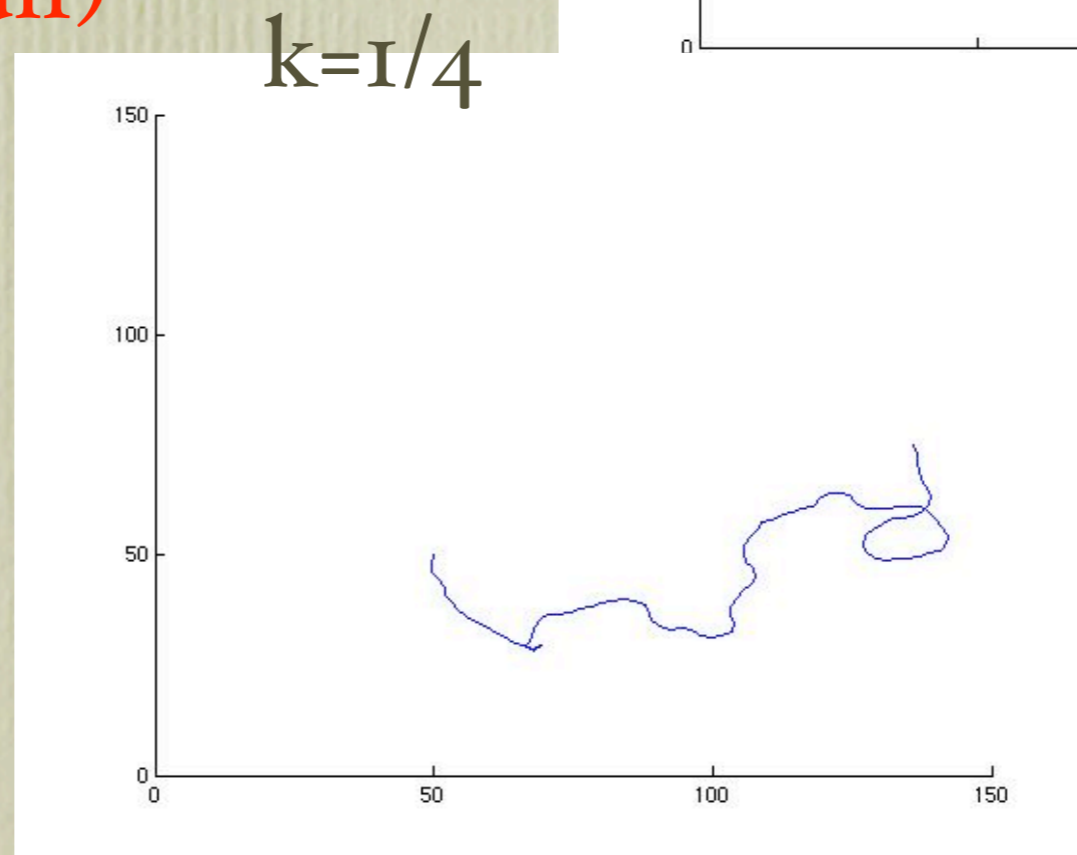
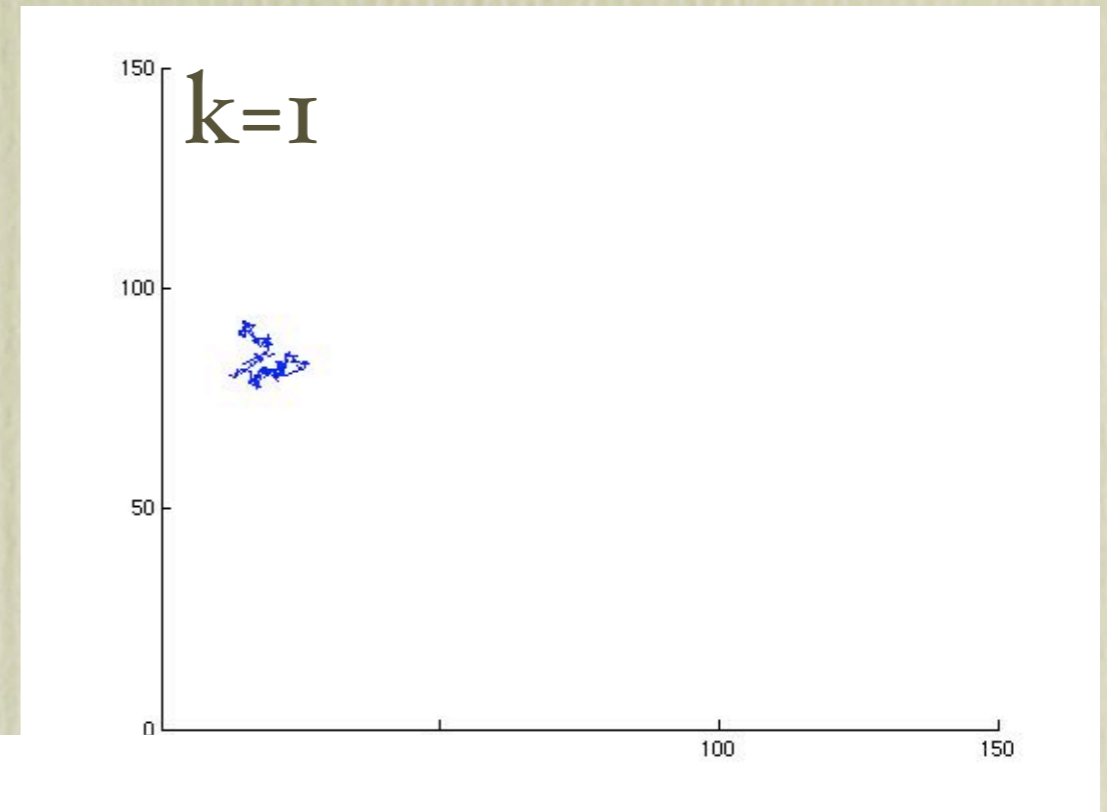
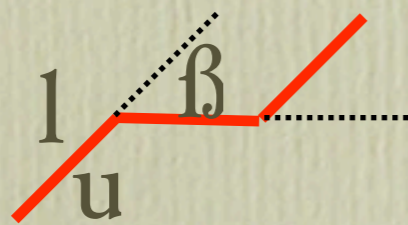
$$\text{dir} = k * 2\pi * (\text{rand} - 0.5) + \text{dir}$$

$$x(t) = x(t-1) + u * \sin(\text{dir})$$

$$y(t) = y(t-1) + u * \cos(\text{dir})$$

next  $t$

plot  $(x, y)$

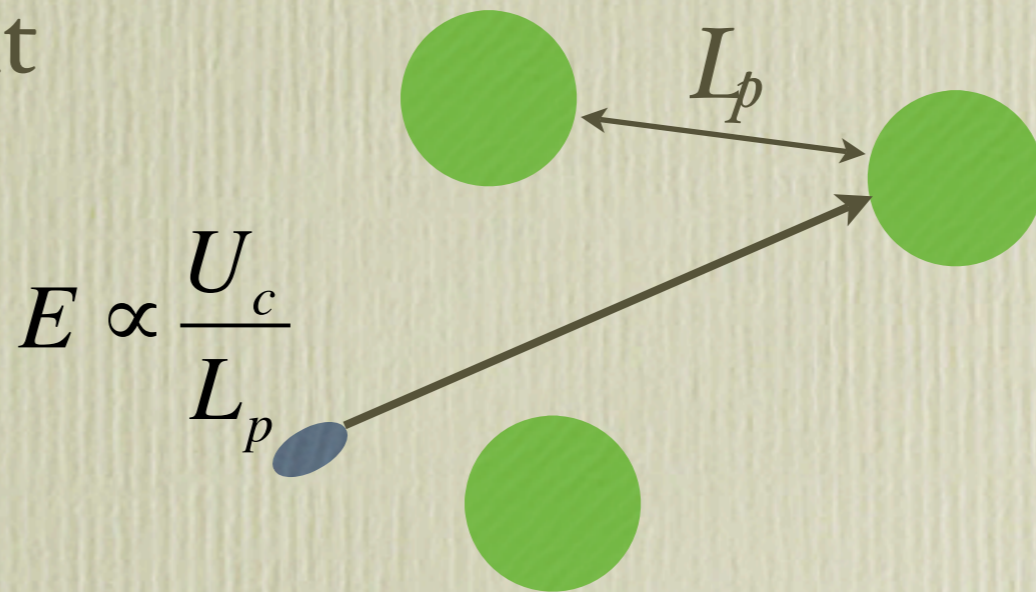


# How to find a patch?

- an encounter problem

● How to search for patches if they cannot be detected from a distance?

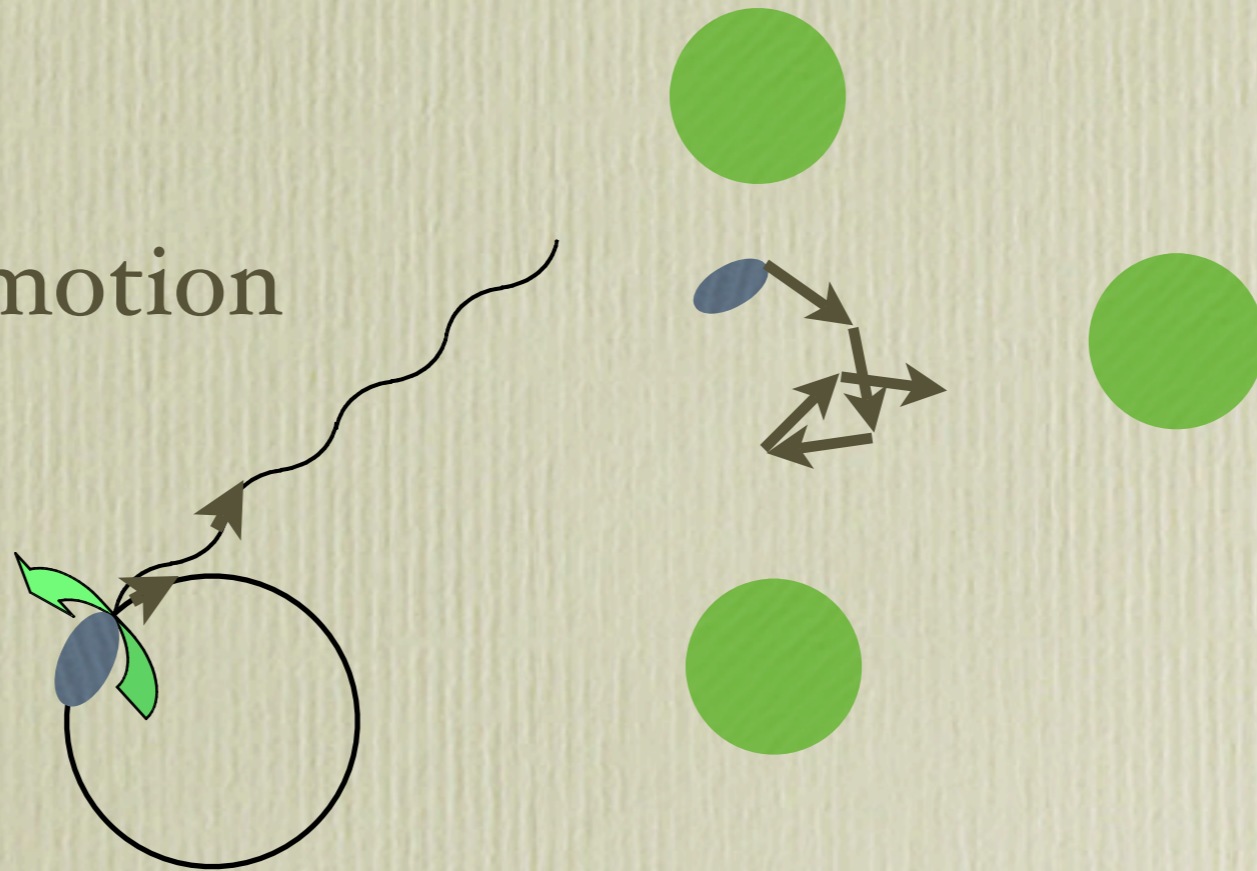
● Ballistic movement



# Constraint for small organisms

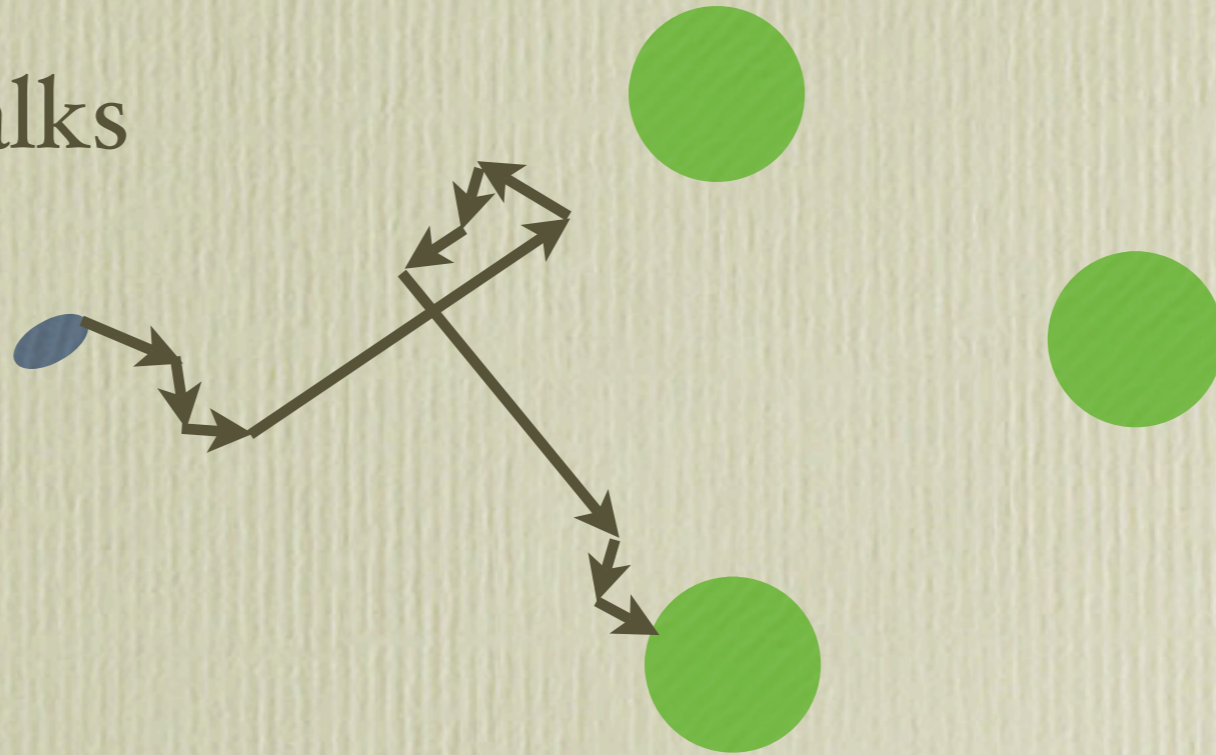
Difficult to move in ballistic paths

Helical motion



# Constraint for small organisms

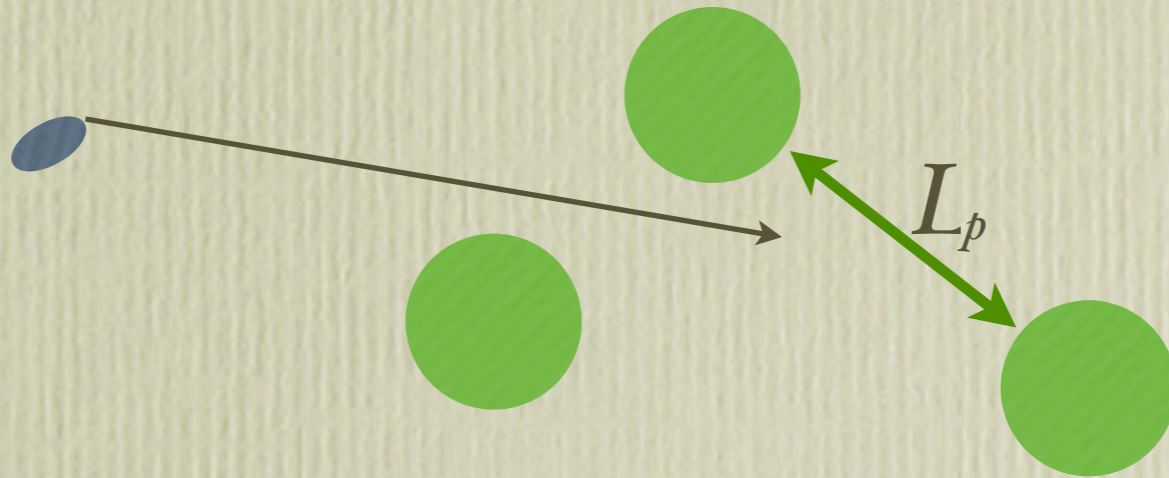
- Minimize crossing the path
- Levy walks



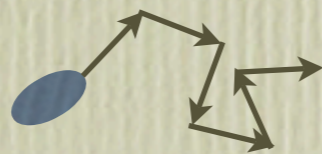
# Encounter rate with patches

- summary

$$E \propto \frac{U_c}{L_p}$$



$$E \propto \frac{4D_c}{L_p^2}$$



$$D_c = \frac{(1 + \overline{\cos(\beta)})U_c l}{4(1 - \overline{\cos(\beta)})}$$

# How fast is patch encounter for a random-walk ciliate?

Typical diffusion constant =  $5 \text{ mm}^2 / \text{s}$   $E \propto \frac{4D_c}{L_p^2}$   $D_c = \frac{(1 + \overline{\cos(\beta)})U_c l}{4(1 - \overline{\cos(\beta)})}$

- Patch distance 1 cm, time to encounter  $\approx 10 \text{ s}$
- Patch distance 10 cm, time to encounter  $\approx 9 \text{ min}$
- Patch distance 1 m, time to encounter  $\approx 14 \text{ h}$

**Ciliate motility can only exploit  
small-scale patchiness!**

# Speculations

- Cues unrelated to food may be used to make movement more ballistic
  - Light
  - Gravity



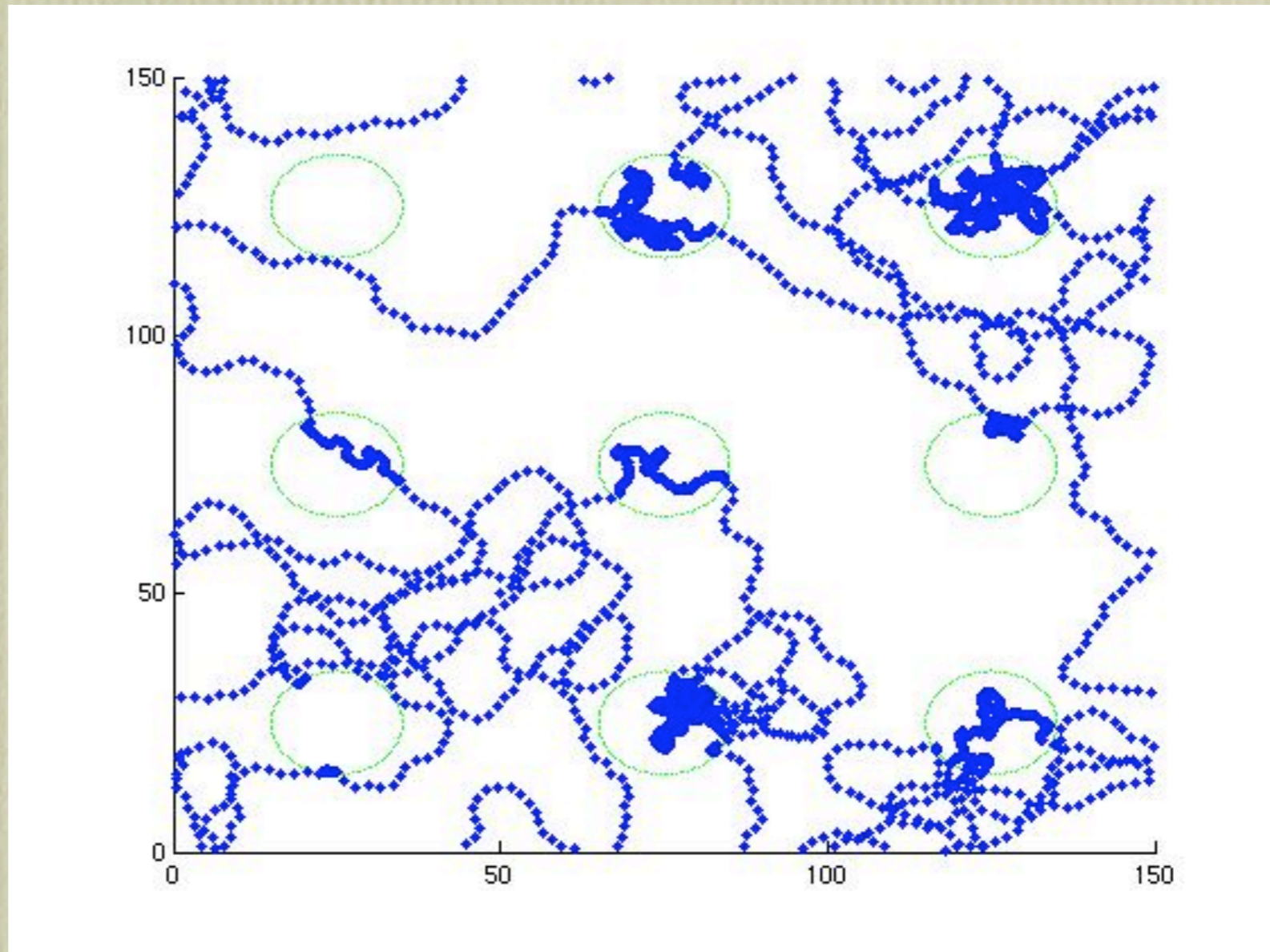
# How does a ciliate stay in a patch?

Response to absolute concentration



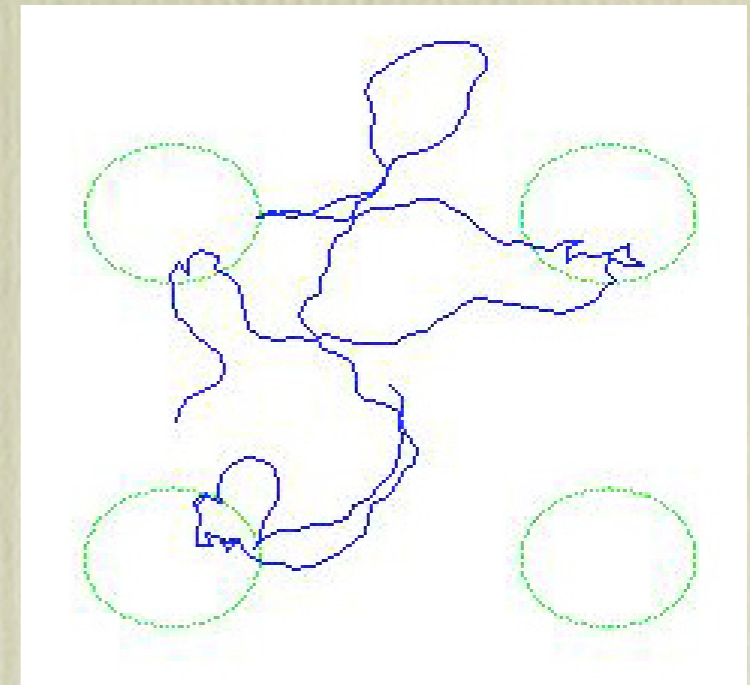
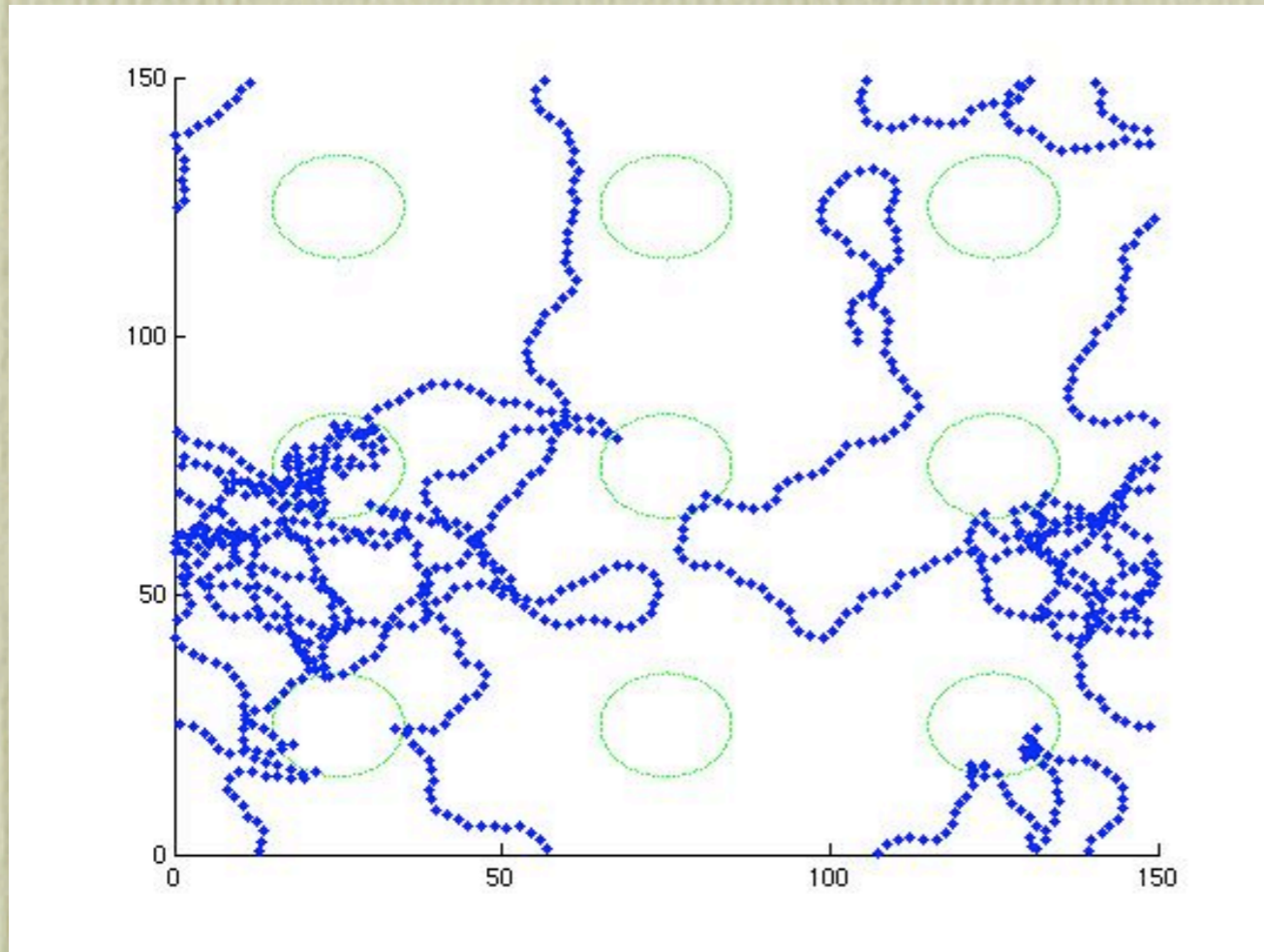
# Slow down in patch

45% of time spent in patches compared to 12% with no response



Reduced velocity in food patch:  
orthokinesis

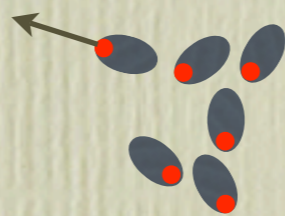
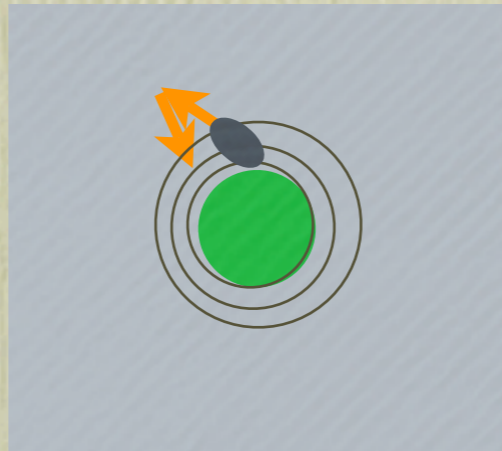
# Increase change of direction in patch



No effect on  
patch time

Change of turning frequency in food patch:  
klinokinesis

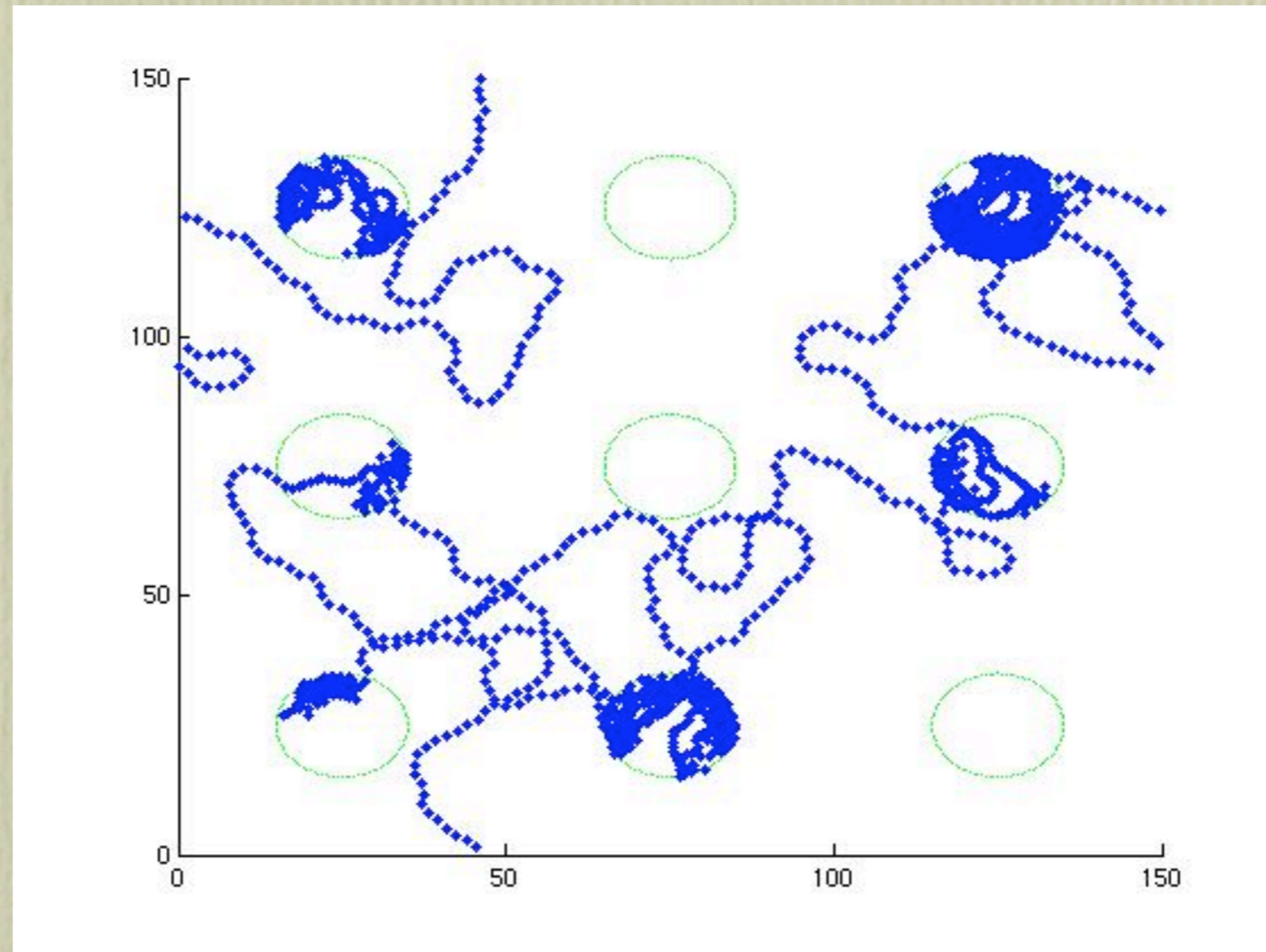
# Response to gradients



Tumble

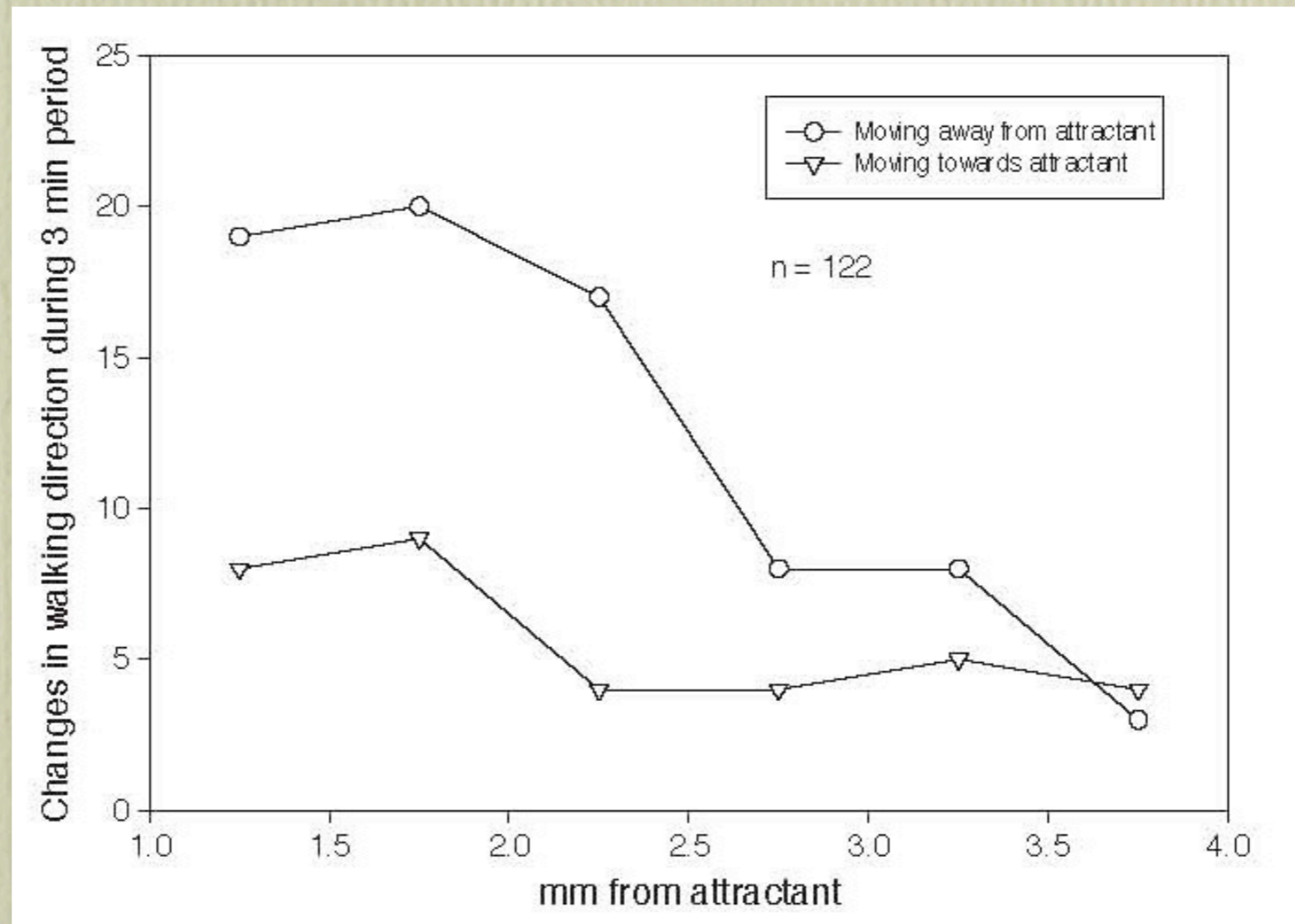
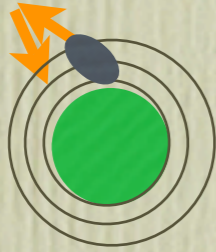
# Model of response to gradients

85% of time spent in patches



transient response to gradients

# Transient response

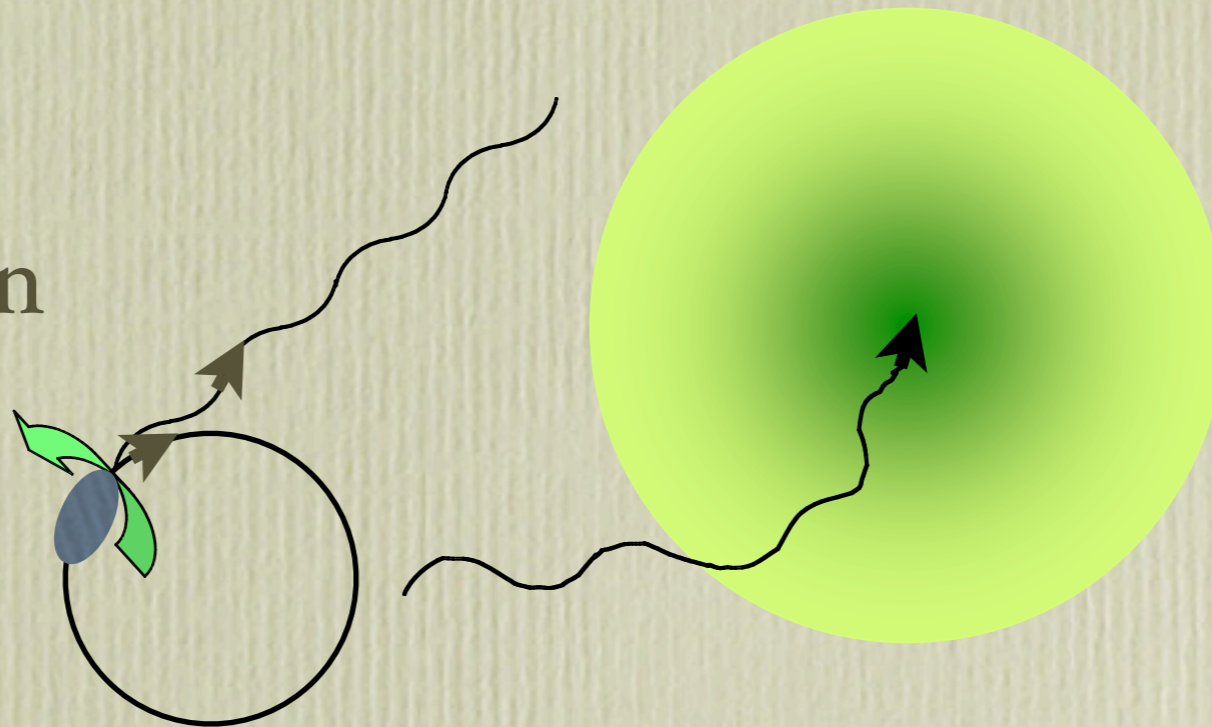


Changes of direction

Fenchel 2004

# Helical klinotaxis

Helical motion



Rotation around the long axis (roll)  
as a function of local concentration

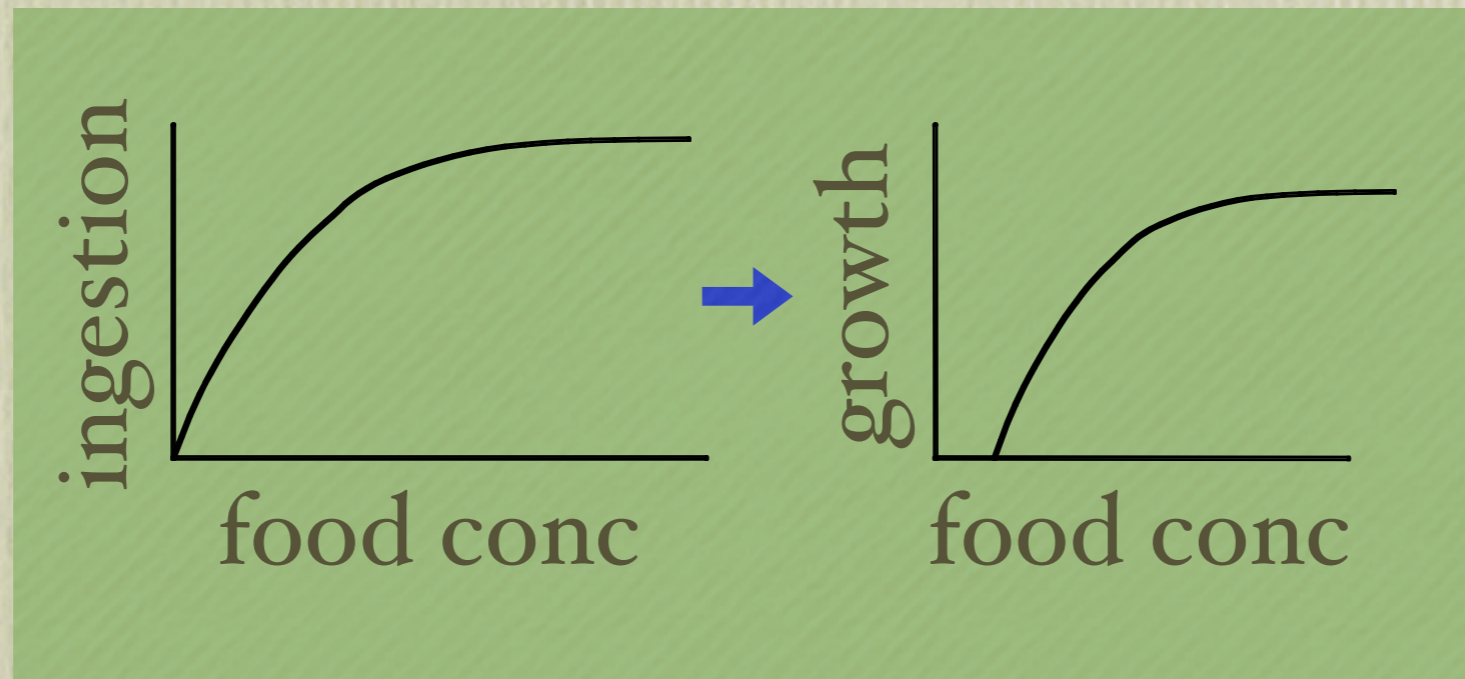
# What do we have so far?

- Random encounter with patches, mainly diffusive process
- Response to both absolute concentrations and gradients
- Change in both speed and turning frequency

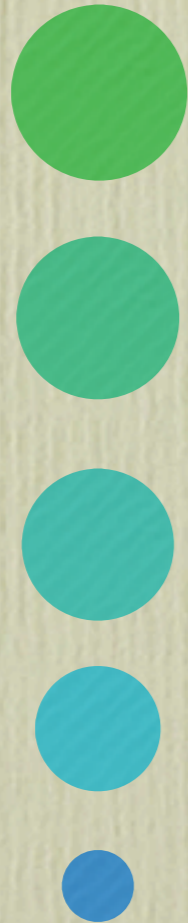
What happens when patch is exploited by successful ciliates?



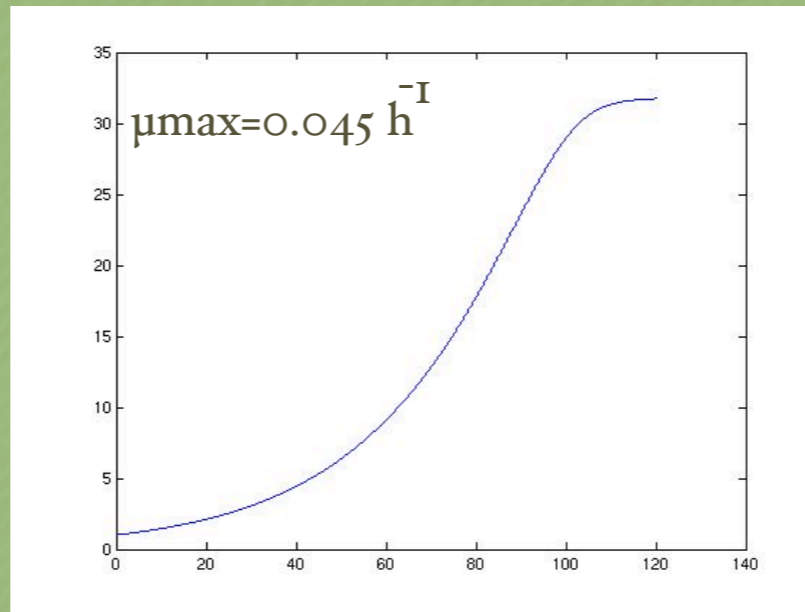
# Food uptake and growth



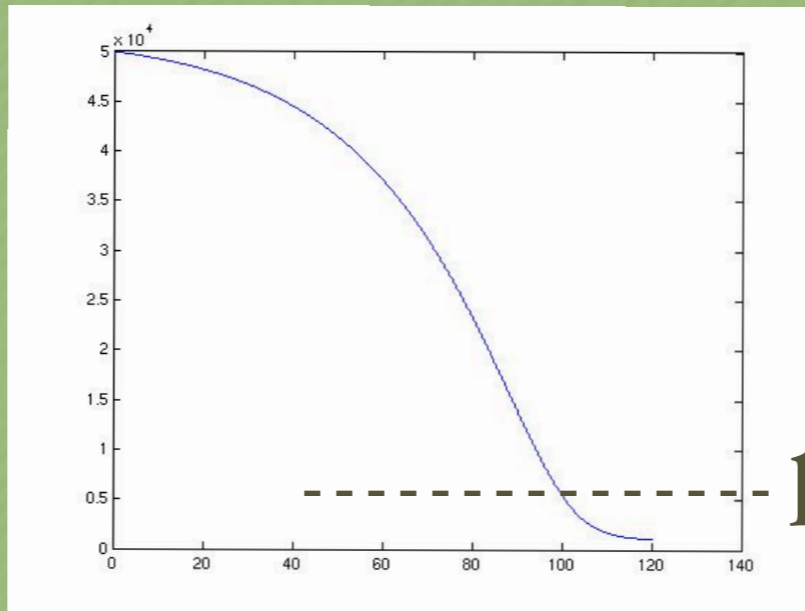
# Depletion of food patch



ciliate

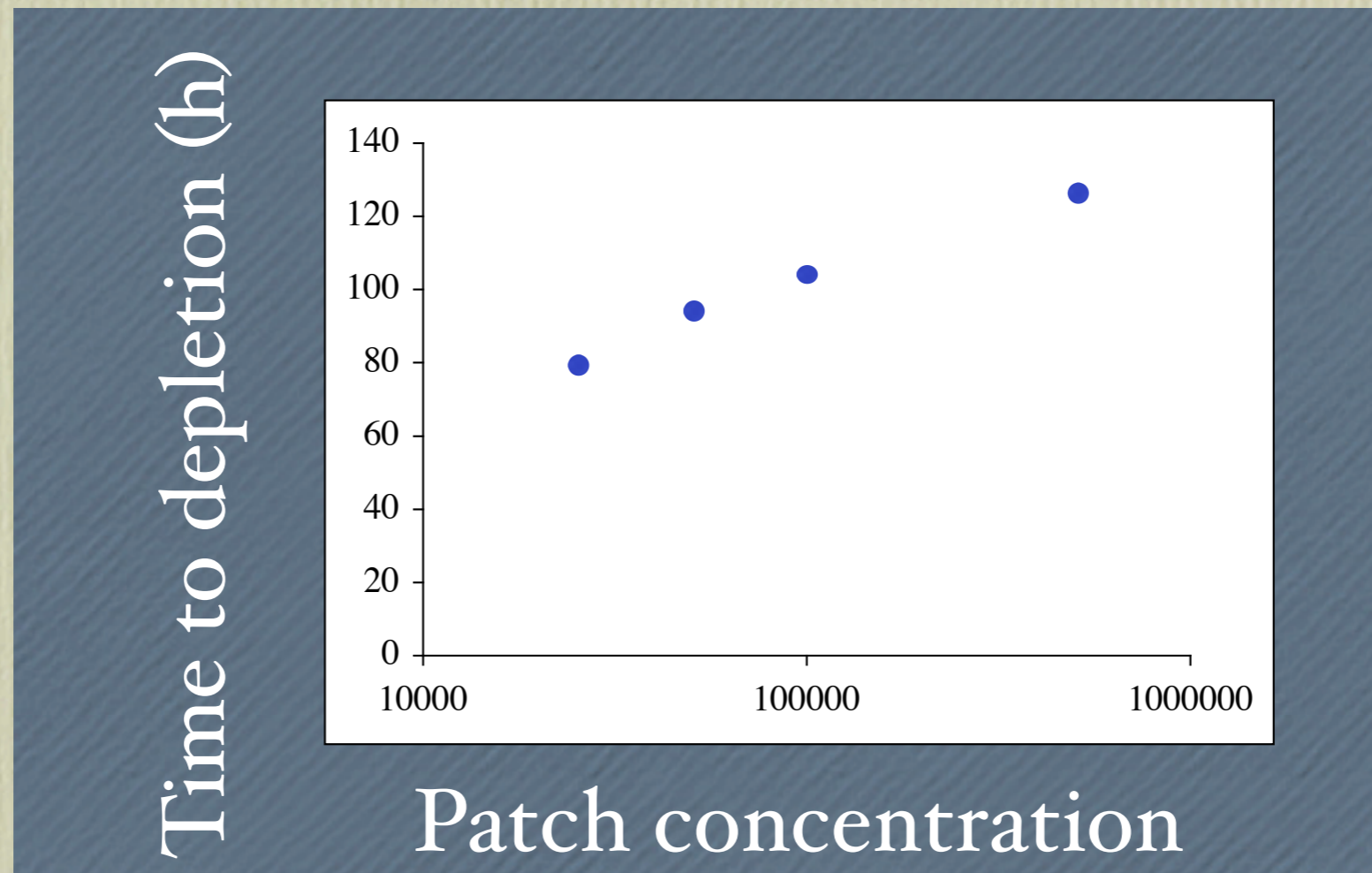


food



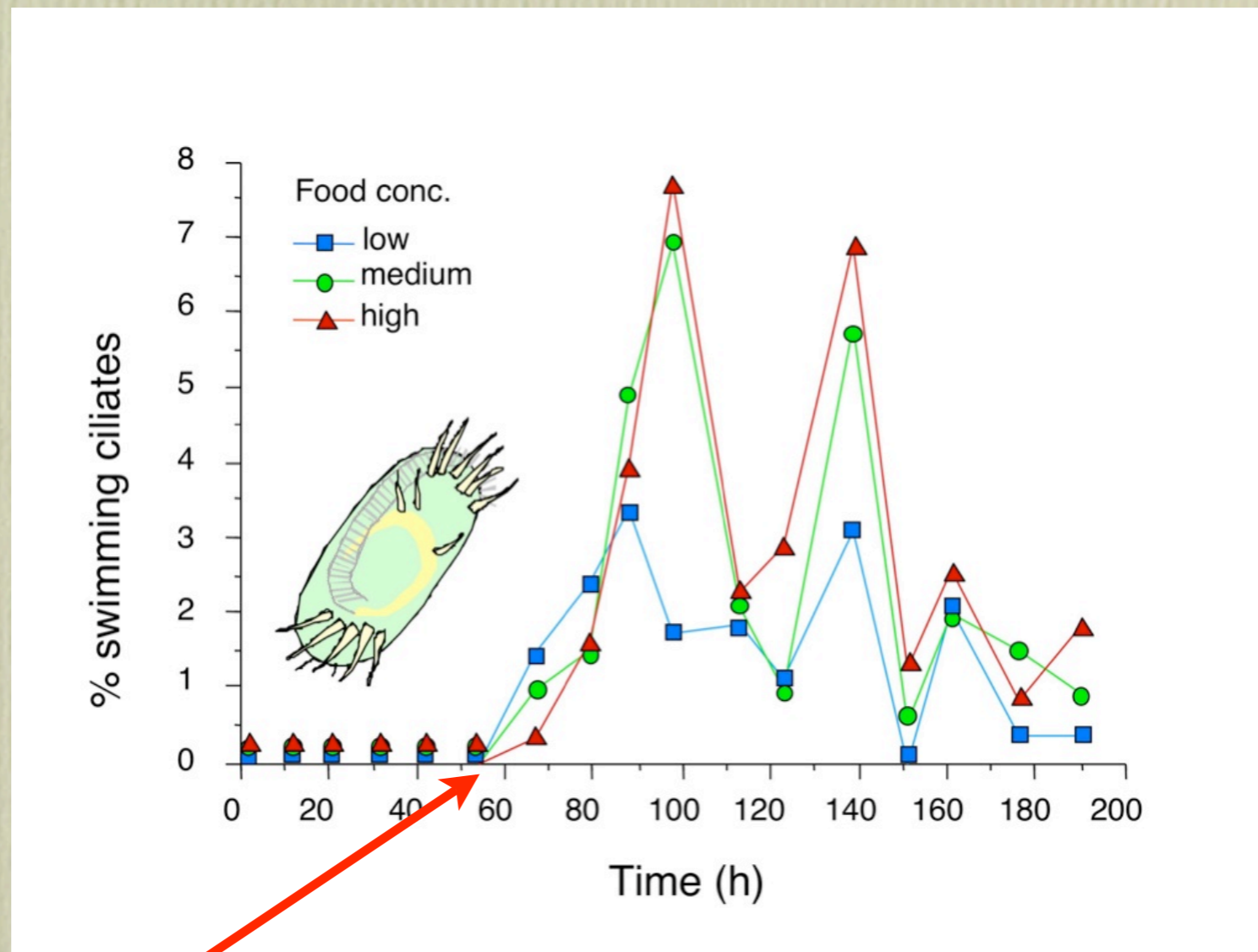
time

# Time to deplete a patch



Exponential growth makes leaving time a  
non-issue

# Dispersal behaviour when food is depleted

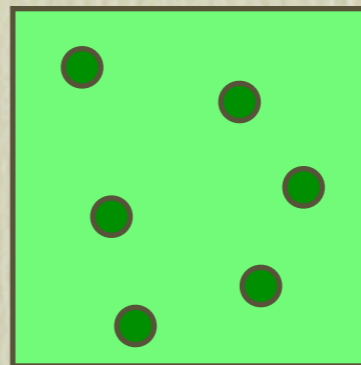
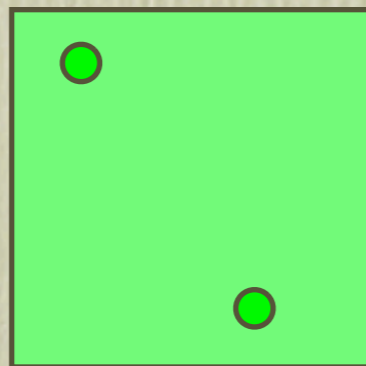
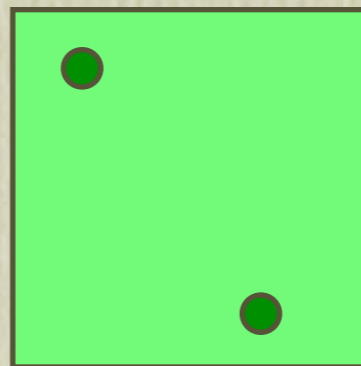
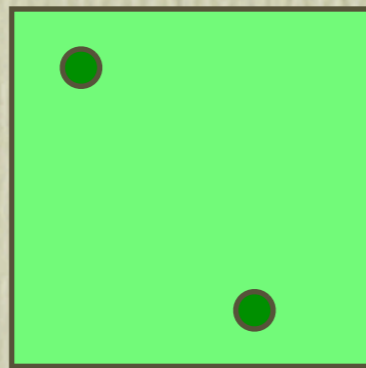


Patch depleted

# Overall model of behavioural advantage

Patch intensity

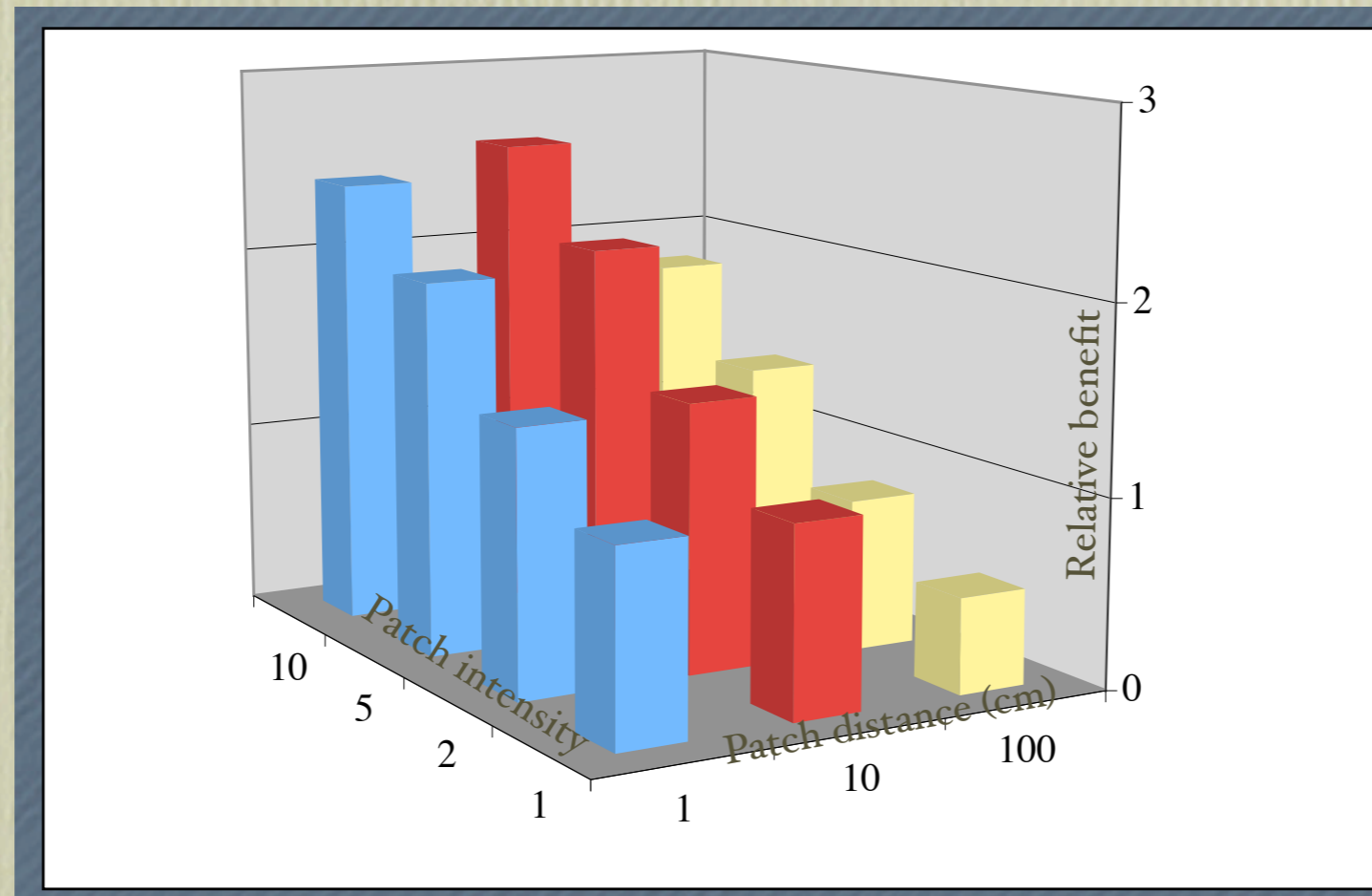
Patch density



# Overall model of behavioural advantage

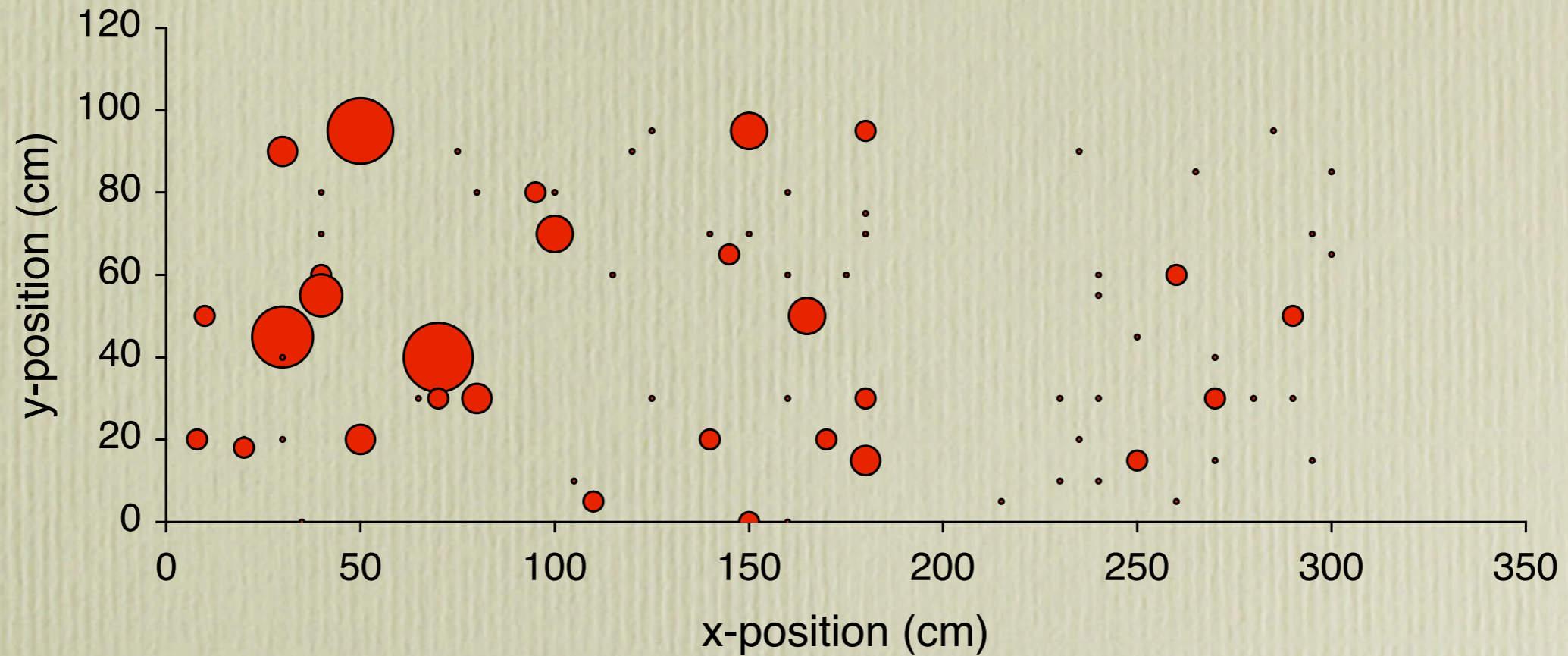
- A ciliate with behaviour disperses to a patch (travel time with no feeding)
- Exploitation leads to population growth and patch is depleted (depletion time)
- This is compared to a naive ciliate which moves randomly in the environment while feeding and growing

# Overall advantage with patch behaviour



**Microbial behaviour strongly increases turnover of carbon and nutrients!!**

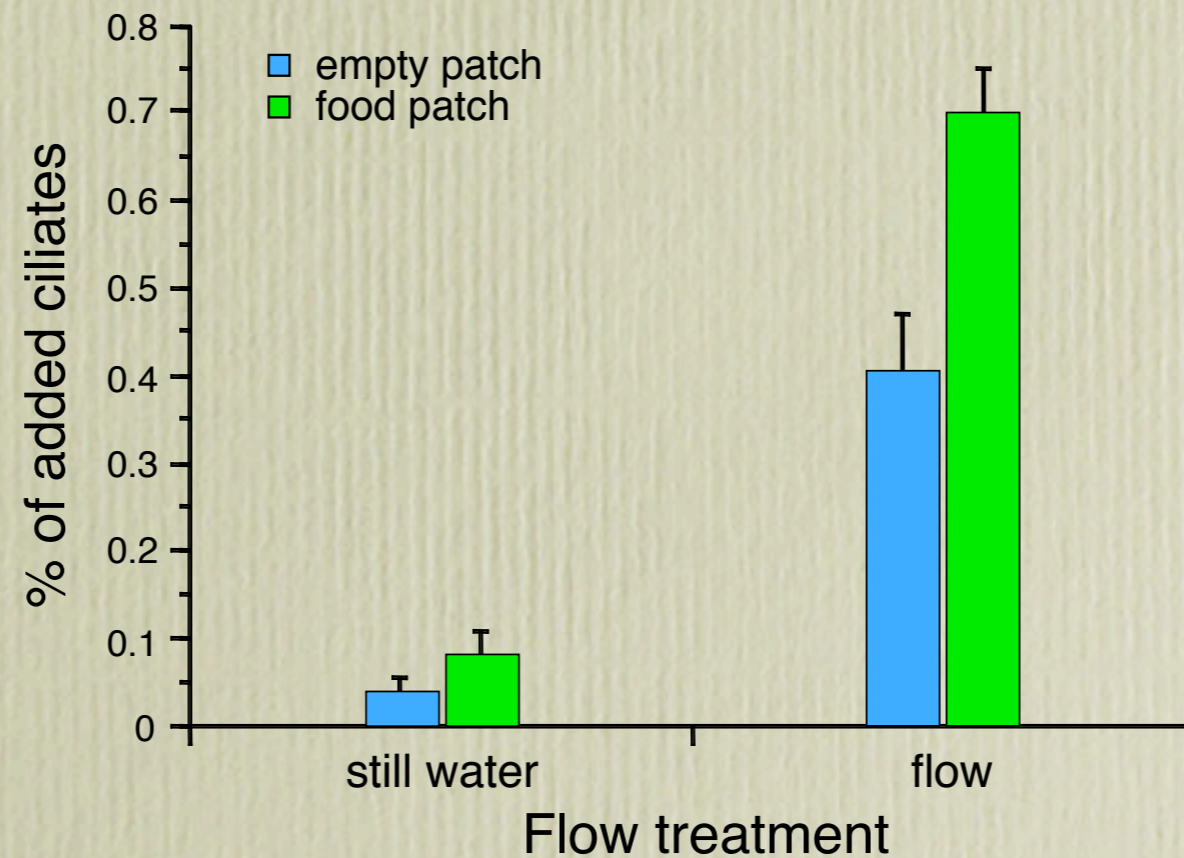
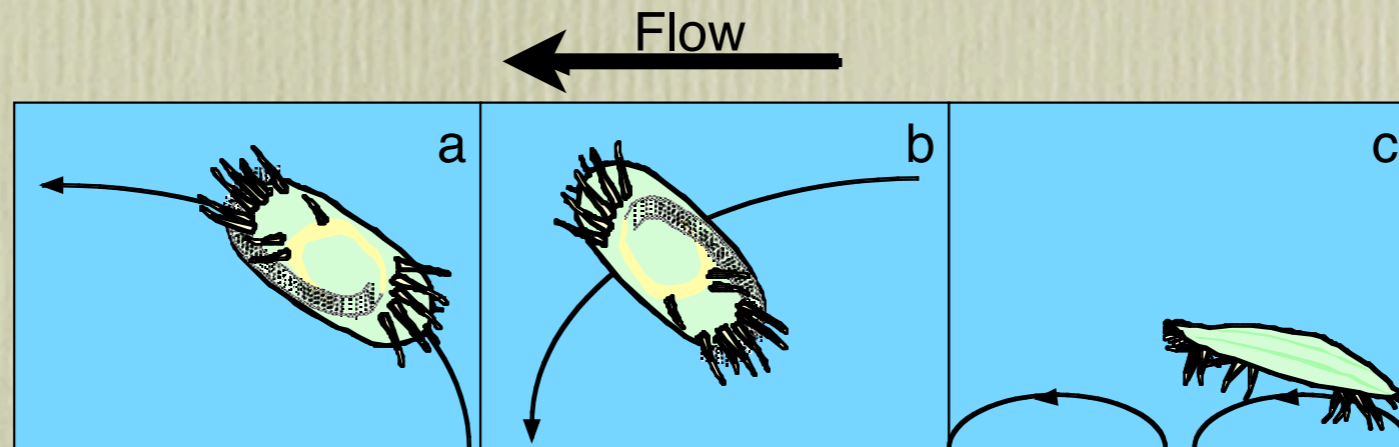
# What is field patch distance?



Indications of 10-20 cm



# In real life dispersal may be more intense



# Conclusions

- “Microbes” often show behavioural responses that increase their fitness in a heterogenous world
- With biological-physical modelling it is possible to analyse behavioural mechanisms and predict ecological significance
- Microbial behaviour likely affects global biogeochemical fluxes

Thank you!

